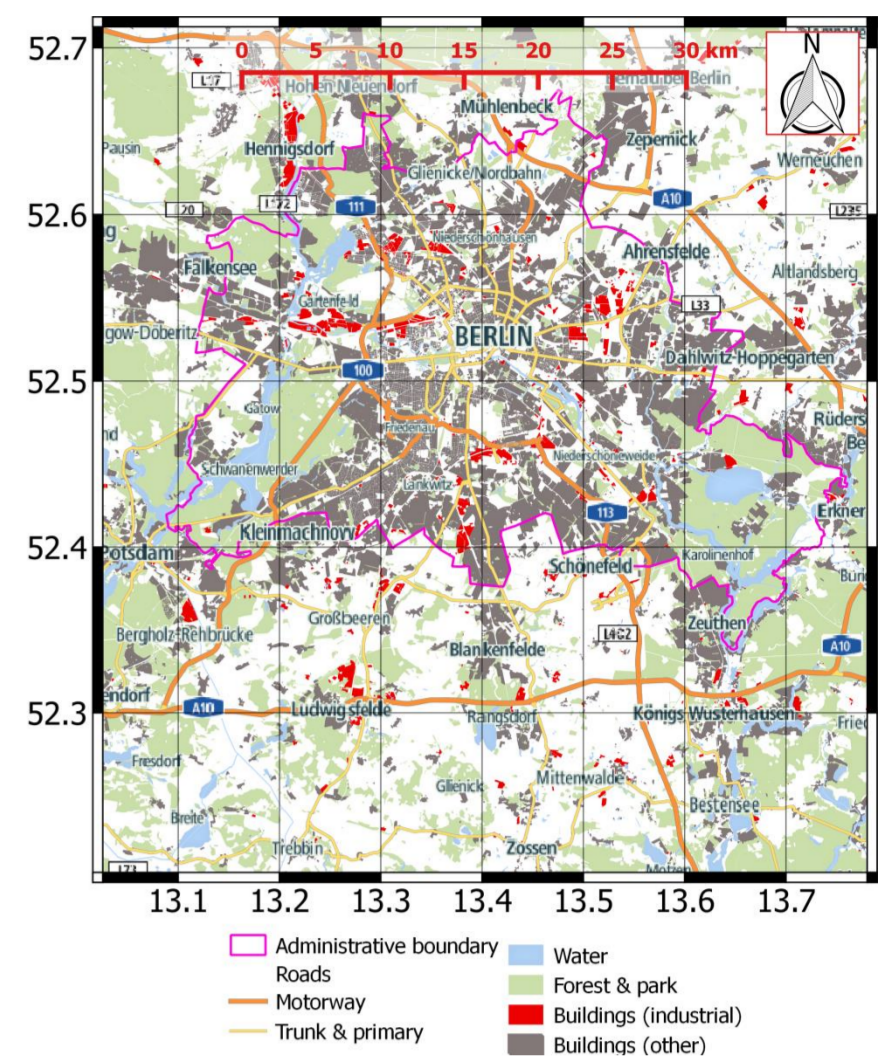


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1. Introduction

- Nitrogen oxides ($\text{NO}_x = \text{NO} + \text{NO}_2$) are:
 - harmful to health and environment and play a key role in atmospheric chemistry
 - a major pollutant in urban areas, despite reduction in the last decades
- Chemical modeling requires knowledge on emissions, which is sparse at high spatial resolution
- Top-down estimates can be used to validate bottom-up inventories

2. Campaigns & target site

- Airborne imaging DOAS measurements performed with the AirMAP instrument, developed at IUP-Bremen on board of the FU Berlin Cessna
- Flights carried out in the framework of the campaigns AROMAT-1 (2014), AROMAT-2 (2015) and AROMAPEX (2016) funded by ESA / EUFAR
- Four mappings of NO_2 , each covering almost the entire city of Berlin
- Berlin is capital and largest city of Germany with about 3.6 million inhabitants

3a. Method for emission estimates

- Basis:** Gauss' divergence theorem, describing the flux (F) of a vector field through a closed surface
- Required input data:
 - Vertical Column Density (VCD) of trace gas
 - Wind vector (\vec{w}) (speed & direction)
 - For NO_x : Correction factor (c_f)
 - Eventually correction for chemical loss (neglected here)

$$F = \oint_S VCD(s) \cdot \vec{n} \cdot \vec{w} \cdot ds$$

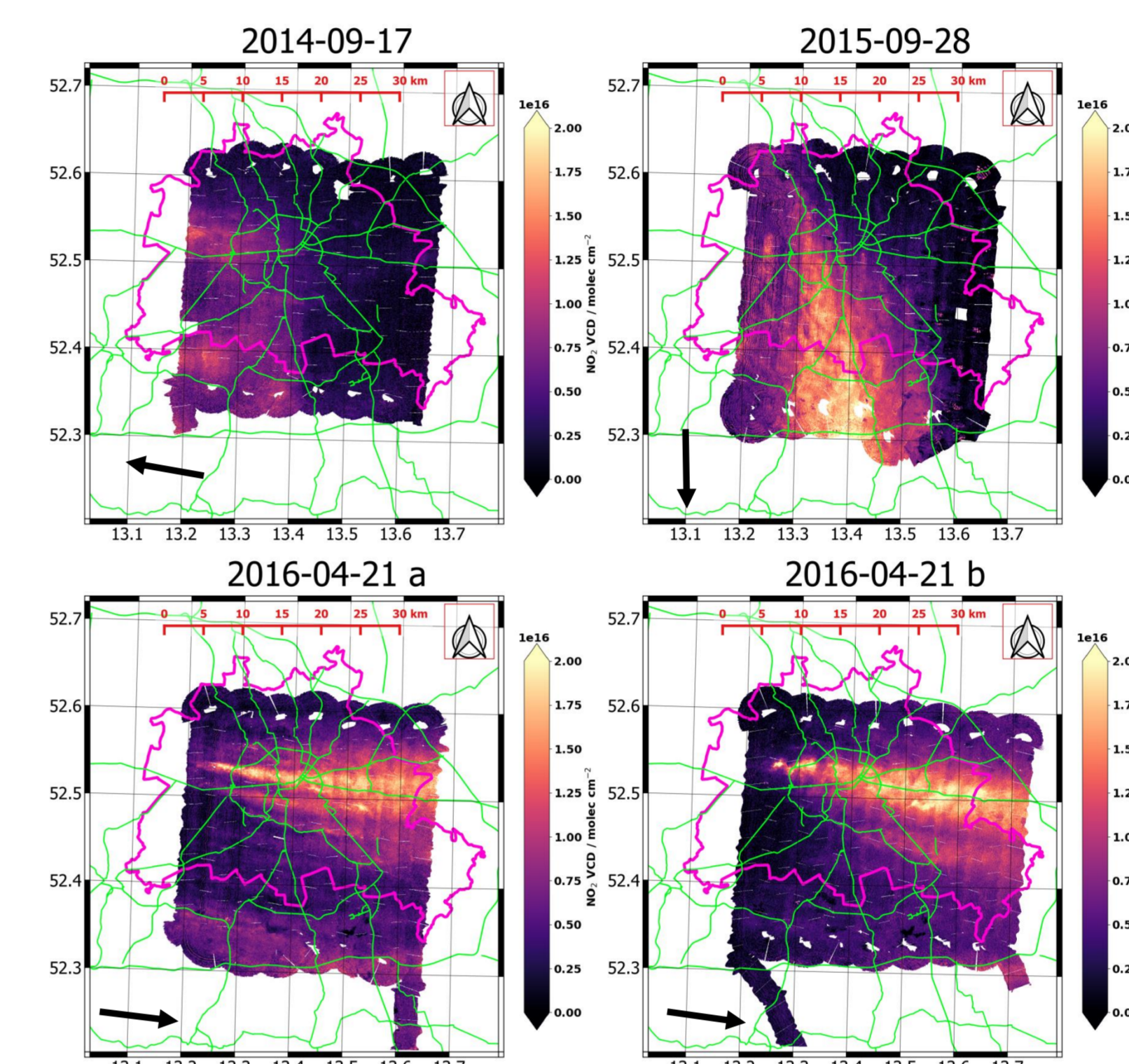
$$\approx \sum_i VCD(s_i) \cdot |\vec{w}_i| \cdot \cos(\beta_i) \cdot \Delta s_i$$

$$c_f = 1 + \frac{[\text{NO}]}{[\text{NO}_2]} ; \text{assumed constant } 1.32$$

$$F_{\text{NO}_x} = F_{\text{NO}_2} \cdot c_f$$

3b. Implementation

1. Gridded NO_2 VCD maps as basis

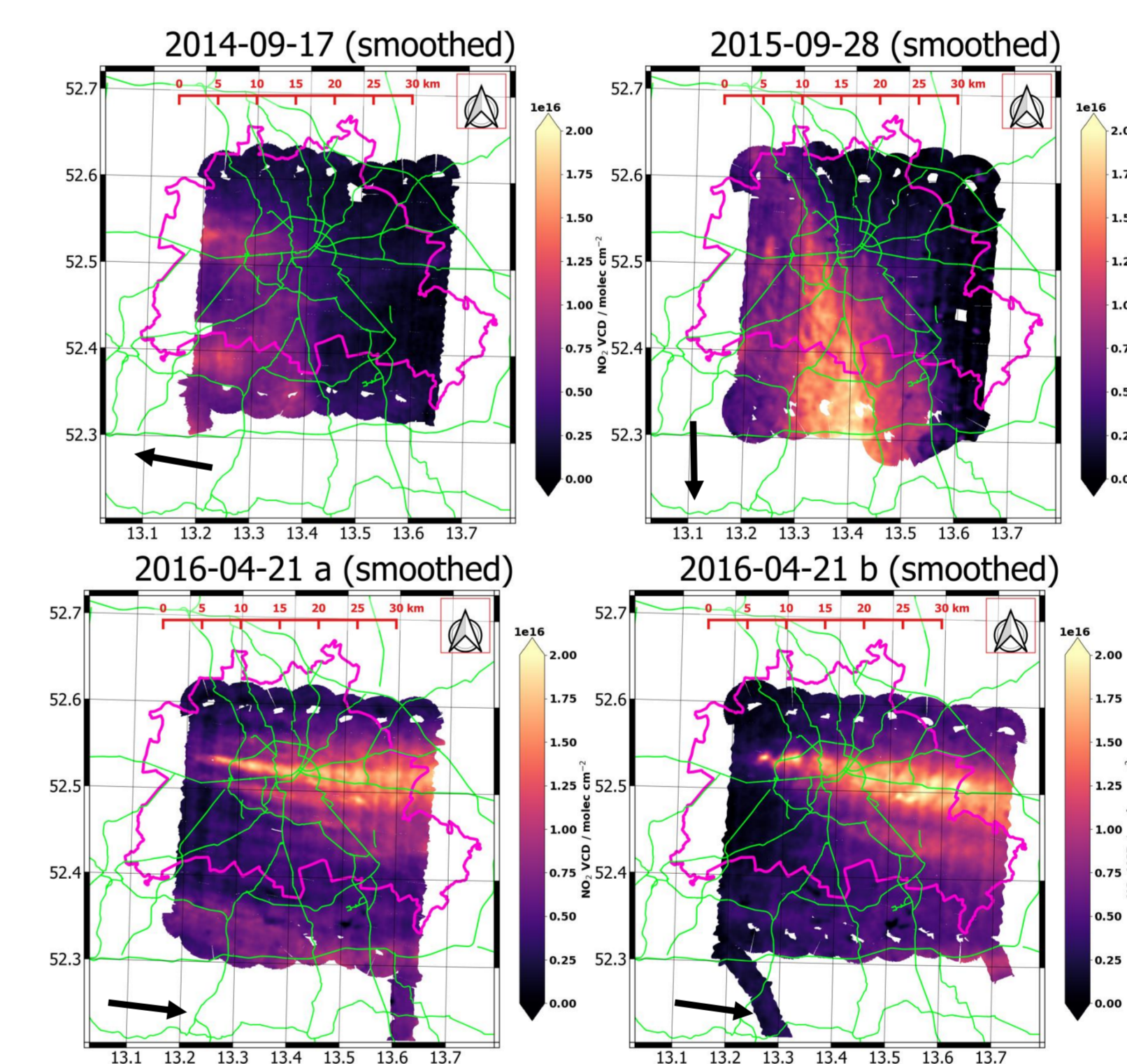


Left: Gridded maps of NO_2 VCD retrieved from four flights on three days above Berlin with the AirMAP instrument

- Different wind directions (easterly, northerly, westerly) lead to distinct spatial patterns

Flight	Wind direction / °	Wind speed / m s ⁻¹
2014-09-17	100	7.8
2015-09-28	359	5.3
2016-04-21 a	277	4.9
2016-04-21 b	278	5.1

2. Smoothing of NO_2 maps to discriminate noise and artifacts



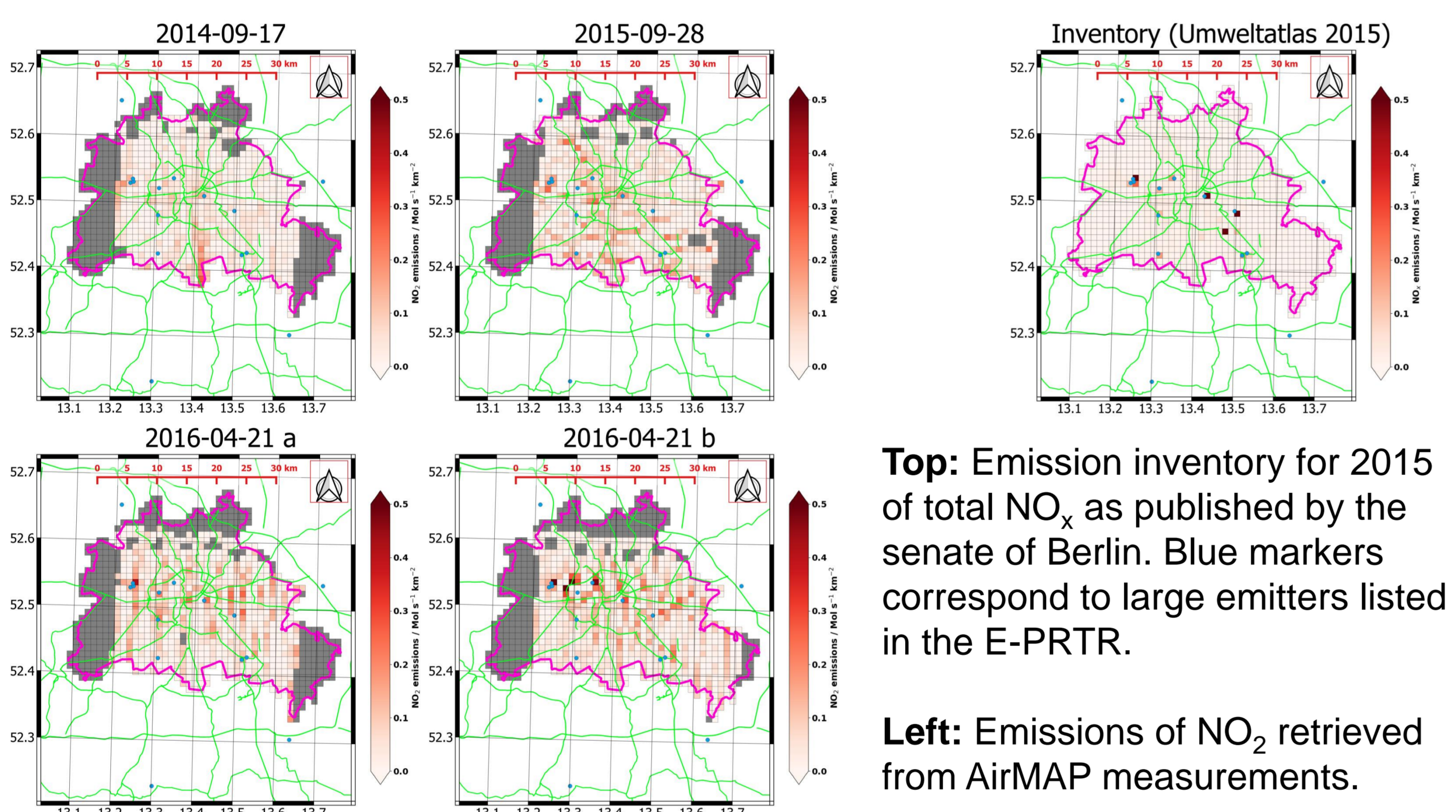
Left: Gridded maps of NO_2 VCD from above convolved with a Gaussian kernel to reduce impact of noise and artifacts from temporal variability

- Little impact of smoothing on general spatial pattern
- Large emitters are readily discernible in the maps

3. Sampling the NO_2 VCD map along the perimeter for each grid cell in a sampling grid

- Here sampling grid is aligned with a high spatial resolution (1km x 1km) emission inventory
- The perimeter of each cell is sampled in steps of 100 m
- Integrating along the perimeter by method in 3a
- Wind speed is interpolated from ERA-Interim reanalysis data, wind direction is determined from the NO_2 maps

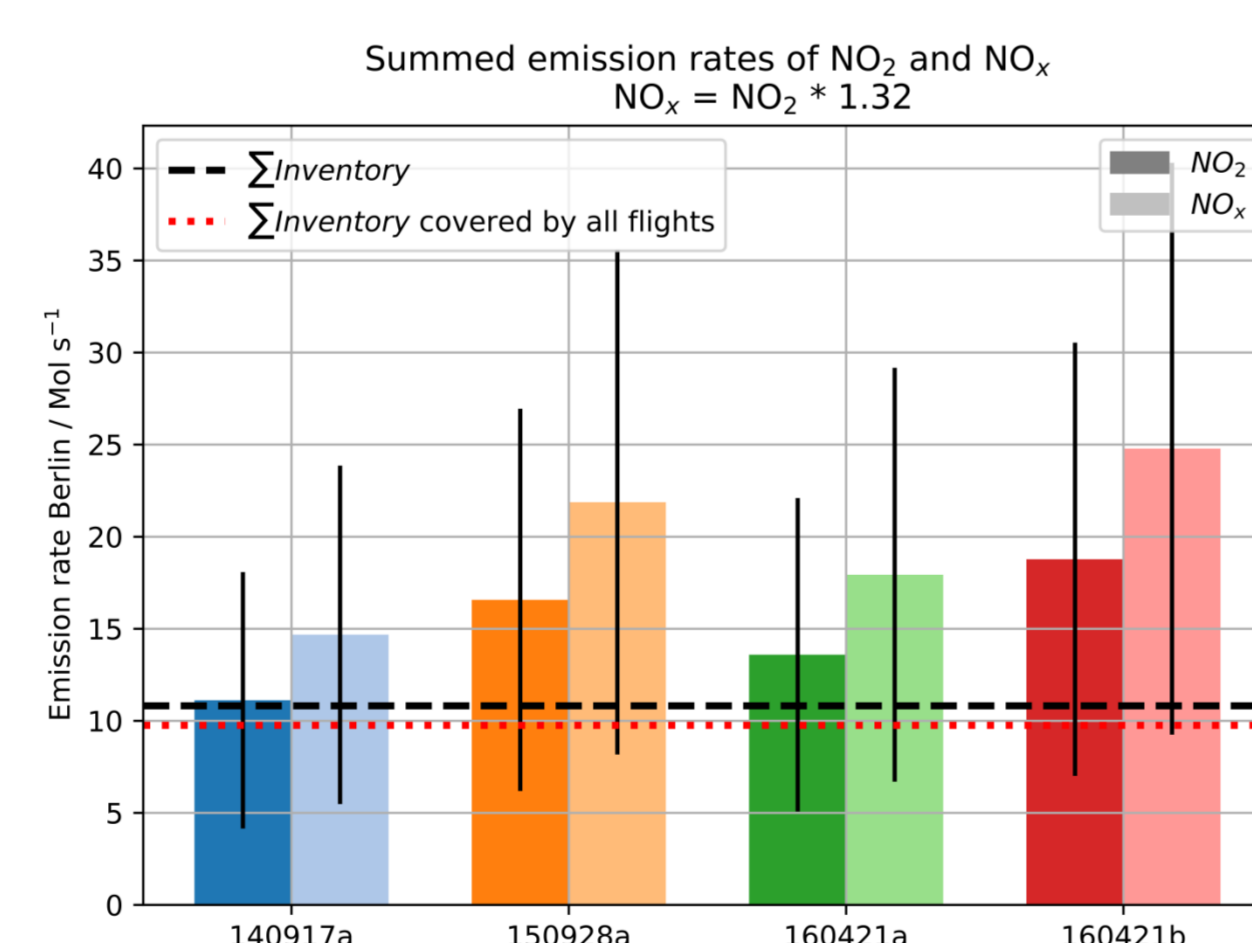
4. Results



Top: Emission inventory for 2015 of total NO_x as published by the senate of Berlin. Blue markers correspond to large emitters listed in the E-PRTR.

Left: Emissions of NO_2 retrieved from AirMAP measurements.

Bottom: Sum of grid cells covered in every flight totaling to 632 km². Error bars estimated from uncertainties in VCD and wind.



- Largest emitter in the north west visible in all emission maps
- Spatial pattern variable between days, 2016 flights show best agreement with inventory
- Small shift between E-PRTR sources and elevated grid cells ($\text{NO} \rightarrow \text{NO}_2$ conversion?)
- Summing over all grid cells gives consistent results
- Retrieved emissions larger than annual average inventory

Selected references

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Acknowledgements

The authors gratefully acknowledge funding of the AROMAT campaigns by ESA, and further financial support by the University of Bremen. Moreover we would like to thank air traffic control for the approval of the research flights and all institutions that contributed to the successful course of the campaign.

5. Summary & Outlook

- Airborne imaging DOAS data from the AirMAP instrument was used to derive emission rates of NO_2 on small spatial scales
- Novel approach based on established concepts
- Retrieved emissions larger than inventory. Large uncertainty from wind data
- Comparison of single days to annual average
- Improving the method requires reliable high-resolution meteorological data, e.g. to calculate accurate trajectories
- The concept can be applied to satellite data

